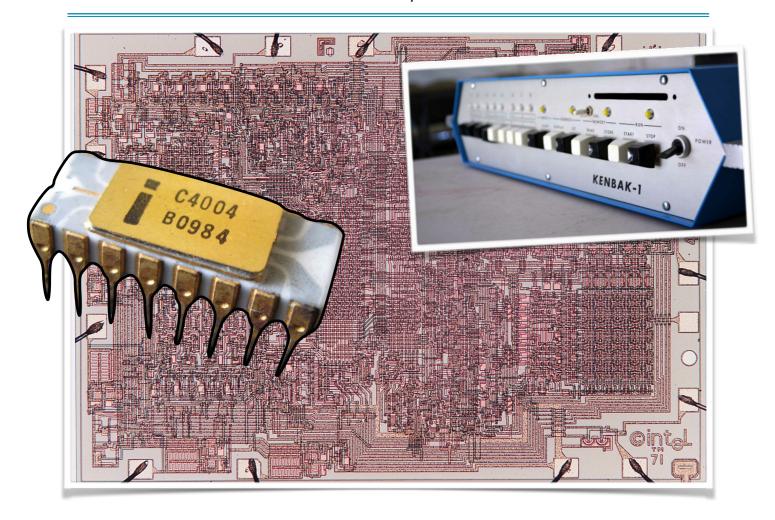
# Réplique du Kenbak-1

Comment fonctionne un microcontrôleur/
microprocesseur et comment ont-t-ils révolutionné
l'informatique ?

Gilles DEVILLERS / Groupe B2 / 2016 - 2017



Université François Rabelais Institut Universitaire et Technologique de Tours Département Génie Électronique et Informatique Industrielle



Groupe 218 Coach: Armel BRUNO



Projet tutoré en autonomie 1ère année Véronique AUGER

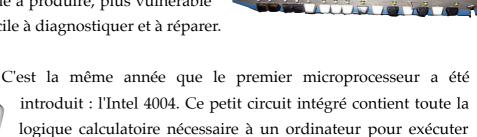
Les microcontrôleurs 1/20 Gilles DEVILLERS

# Introduction

Dans le cadre de notre projet tutoré en autonomie de 1ère année, nous avons choisi de réaliser une réplique fonctionnelle du Kenbak-1 : le premier ordinateur pour particuliers disponible dans le commerce. À sa sortie en 1971, il était possible de l'acheter en magasin, de le brancher et de directement commencer à l'utiliser. C'était une très grande avancée pour l'informatique personnelle. Avant cela, l'informatique était réservée aux hobbyistes confirmés qui devaient acheter un kit, le souder et le débogguer eux-mêmes.



Une des particularités du Kenbak-1, réalisé uniquement par John Blankenbaker, était d'être dépourvu de microprocesseur (ou de microcontrôleur de façon plus générale). Toute la logique qui permettait à cet ordinateur de fonctionner était réalisée et câblée « à la main ». Ce qui le rendait encombrant, lourd, cher, plus long et difficile à produire, plus vulnérable aux pannes et plus difficile à diagnostiquer et à réparer.



Plus tard, le TMS1000 et l'Intel 8008 furent les premiers microcontrôleurs, regroupant cette fois-ci, en plus de la logique, de

la mémoire, une horloge et d'autres périphériques les rendant complètement autonomes.

des programmes.

Cette recherche documentaire va donc apporter des éléments de réponse à la problématique suivante : comment fonctionne un microcontrôleur et comment ont-ils révolutionné l'informatique ?

# **Bibliographie**

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- 2. **In One Lesson**. *How a CPU Works*, 15 mars 2013. (vidéo consultée le 26 mars 2017) < <a href="https://youtu.be/cNN\_tTXABUA">https://youtu.be/cNN\_tTXABUA</a>>
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Les microcontrôleurs 3/20 Gilles DEVILLERS

# **Mots-clés**

- Informatique
- Microcontrôleur
- Microprocesseur
- Logique
- Combinatoire
- Séquentiel
- Mémoire
- Stockage
- Architecture
- Harvard
- Von Neumann

- RISC
- Composants
- Transistors
- Révolution
- Connecté
- Communication
- Interface
- Intelligent
- Optimisation
- Encombrement
- Circuits intégrés

# **Annexe 1 I How Microcontrollers Work**

## Identification

• <u>Adresse de l'article</u>: https://stratifylabs.co/embedded%20design%20tips/2013/10/14/Tips-How-Microcontrollers-Work/

• Nom du site: Stratify Labs

<u>Date de publication</u>: 14 octobre 2013
<u>Date de consultation</u>: 26 mars 2017

## Évaluation du contenu

Critère d'évaluation	Faible	Moyen	Bien	Très bien
Degré de fiabilité de l'informatique				X
Utilité, accessibilité, pertinence de ces informations				X
Utilité des illustrations				X
Qualité, nombre				X

## Mots clés

Microcontrôleur

• Logique

Transistor

Architecture

Silicium

Bascule

# Compte rendu

L'article est découpé en cinq parties, partant du très bas niveau et allant jusqu'au bas niveau du fonctionnement d'un **microcontrôleur**.

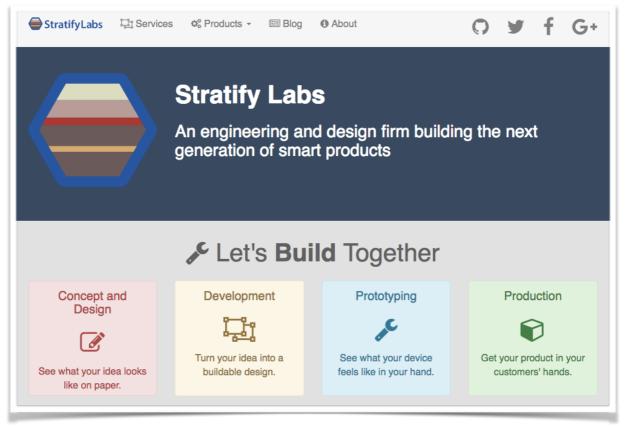
- 1. Les <u>semi-conducteurs</u>: les éléments physiques utilisés dans tout circuit électronique. Notamment le **silicium** et ses électrons libres qui permettent à un courant électrique de circuler dans ce matériau.
- 2. Les <u>transistors</u>: comment sont assemblés les éléments physiques afin de réaliser des « **jonctions** ». Dans le cas du transistor, ces jonctions font office d'interrupteur contrôlé par un courant électrique plutôt que par un Homme.

- 3. <u>Portes logiques</u>: en assemblant les transistors de différentes manières, on obtient des éléments appelées portes logiques qui laissent passer le courant électrique sous certaines **conditions**.
- 4. <u>Logique combinatoire et séquentielle</u>: ces portes logiques sont elles aussi assemblées de différentes façons afin d'obtenir des systèmes capables d'**additionner** des nombres, de les **mémoriser**, etc.
- 5. <u>L'architecture</u>: tous ces circuits logiques individuels (mémoire, processeur...) **communiquent** d'une certaine façon qui est propre à chaque famille de microcontrôleur.

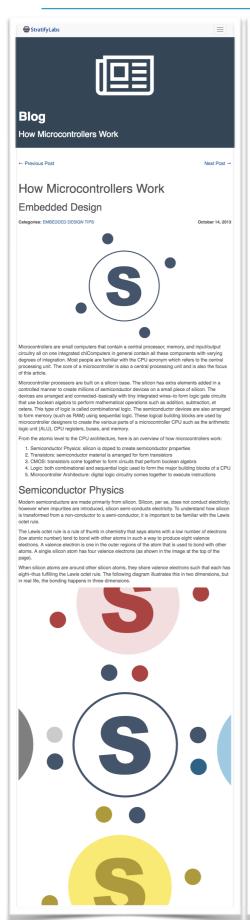
## **Avis**

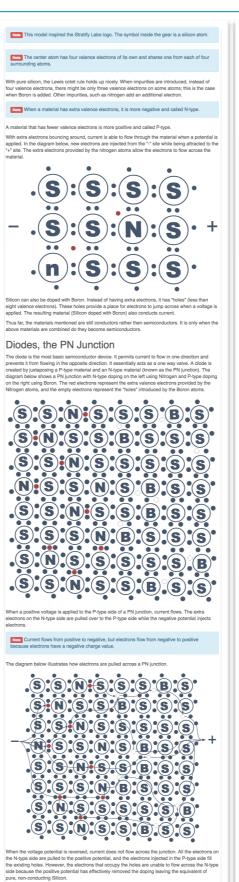
Cet article est un plaisir à lire. Il suit une progression très logique, partant du très bas niveau jusqu'au haut niveau en expliquant simplement et efficacement les différentes parties et comment elles interviennent les unes avec les autres. L'autre rentre juste assez dans les détails pour rester intéressant mais pas trop pour ne pas devenir ennuyeux. Les schémas, très simples, sont d'une grande aide à la compréhension des concepts présentés.

J'attribue une note de 10/10 à cet article pour sa clarté et sa cohérence avec le sujet de cette recherche documentaire.



Page d'accueil du site



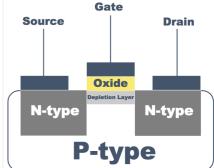


The diode is the most basic semiconductor device. However, it is not the main building block or

#### Field Effect Transistors (FETs)

The first widely-used transistors were the bi-polar junction transistors (BJTs). They are created by using an additional doping material with the PN junction resulting in either an NPN or PNP transist However, BJTs are better at amplification than switching. The second widely used transistors were the Field effect transistors (FETs), FETs are typically "or" or "of" and rarely operate in the linear region between these states making them well-culted as they switches.

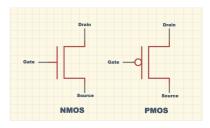
FETs also use N-type and P-type materials but they are arranged distinctly. The metal-oxidesemiconductor FET (MOSFET) was the first FET and one of the most common in use today. The diagram below shows the anatomy of an N-channel MOSFET (or NMOS).



The MMOS consists of a P-type substrate with two N-type regions connected to the source and drini. The gate is connected to the substrate through an insulating coids layer (electrically it acts as a capacitor). The gate is used to control whether the switch is on or off. When the gate-source voltage is 0V, the substrate acts like two cloidses that are builted together in poposite directions preventing current flow in both directions. When the gate-source voltage is above a threshold, the positive charge on the gate pushes event the positive charged notice? In the P-type region and attracts negatively charged electrons creating a depletion layer that is effectively a channel of N-type

P-channel MOSFET (PMOS) has the same structure but uses an N-type material for the substrate ind P-type for the drain and source connections. Also the gate-source voltage must be below a ertain (negative) threshold to turn on.

In practice, the source of an NMOS is almost always connected to ground while the source of a PMOS is mostly connected to VDD. This is especially true in single supply systems. This configuration makes it easy to apply a positive voltage to the NMOS gate and a negative voltage to the PMOS gate (both voltages being with respect to the source). The diagram below shows simplified schematic symbols for NMOS and PMOS transistors. Though the the symbols have horizontal symmetry, the conventional wisdom mentioned above holds true for subsequent illustrations meaning NMOS source is down (ground) and PMOS source is up (VDD).



NMOS and PMOS transistors work complementary to form what is called CMOS logic-the C signifies complementary.

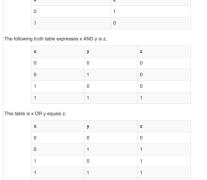
#### CMOS

CMOS stands for complementary metal-oxide-semiconductor and is the result of using NMOS and PMOS transistors together to create logic gates. To grasp the importance of CMOS logic, understanding boolean algebra is crucial.

#### Boolean Algebra

Boolean algebra is named after George Boole who published a book called An Investigation of the Laws of Thought in 1654. In this book, he defined an algebraic system based on the values of 0 and In The operations defined are distinct to decimal number operations such as plus and minus as well as multiply and divide. Nonethieless, these boolean operations are the building blocks for implementing traditional algebraic operations using CMOS circuitry.

The basic boolean operators are NOT, AND, and OR. While AND as well as OR have two or more inputs, NOT operates on a single input value. Boolean operations are typically expressed using a truth table (a table of inputs and outputs). Here is the truth table for x NOT equals z.



These operations can also be combined. NOR is a combination of NOT and OR where NOT is applied to the output of OR. Additionally, NAND is NOT applied to the output of AND. These combinations are important for building CMOS circuitry of these operations. To start building these operators with CMOS circuitry, the CMOS inverter performs the NOT operation.

01100

# Extrait de l'article consulté

SSNSSS

## Annexe 2 I How a CPU Works

## Identification

• Adresse de la vidéo : https://youtu.be/cNN\_tTXABUA

• Nom du site: Youtube

• Réalisateur : In One Lesson

Date de publication : 15 mars 2013Date de consultation : 26 mars 2017

## Évaluation du contenu

Critère d'évaluation	Faible	Moyen	Bien	Très bien
Degré de fiabilité de l'informatique			X	
Utilité, accessibilité, pertinence de ces informations			X	
Utilité des illustrations				X
Qualité, nombre				X

## Mots clés

- Microcontrôleur
- Architecture
- Unité de contrôle
- Logique
- Programmation
- Mémoire vive
- Assembleur
- Bus de données
- Instructions

# Compte rendu

Cette vidéo, inspirée du livre « *But How Do It Know* » de John Scott, explique principalement le **fonctionnement** interne du **microprocesseur**, élément principal d'un **microcontrôleur**. Contrairement au document précédent, l'auteur part du haut niveau pour aller vers le bas niveau du fonctionnement du microprocesseur.

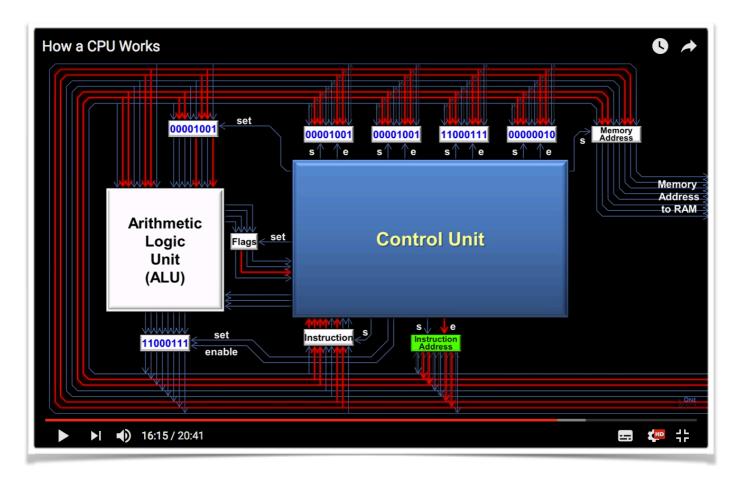
Chaque partie du microprocesseur est détaillée. Premièrement l'architecture Von Neumann et le stockage des instructions sous forme binaire dans la mémoire vive. Puis la

façon dont l'unité de contrôle gère les opérations et les transferts de données entre l'UAL (Unité Arithmétique et Logique, chargée d'effectuer les calculs) et les registres (mémoire temporaire). Le bus de données principal montre l'interface entre le processeur et les mémoires ou périphériques externes.

## **Avis**

La vidéo explique le fonctionnement d'un microprocesseur de façon simple. Il est intéressant de le mettre en perspective du premier article pour avoir plus de détails sur le fonctionnement global du microprocesseur et sa communication avec la mémoire vive. On comprend bien la façon de programmer un microcontrôleur et comment les programmes sont exécutés sur une architecture Von Neumann.

J'attribue à cette vidéo la note de 8/10 car bien que son accessibilité en face son intérêt, quelques détails supplémentaires pourraient être souhaités comme le fonctionnement interne de l'unité de contrôle.



Capture d'écran de la vidéo

# Annexe 3 I AVR Microcontrollers for High-Performance and Power-Efficient 8-bit Processing

## Identification

Auteur : Atmel Corporation

• <u>Titre</u>: AVR Microcontrollers for High Performance and Power-Efficient 8-bit

Processing

• <u>Date de 1<sup>ère</sup> parution</u>: 2013

## Évaluation du contenu

Critère d'évaluation	Faible	Moyen	Bien	Très bien
Degré de fiabilité de l'informatique				X
Utilité, accessibilité, pertinence de ces informations			X	
Utilité des illustrations				X
Qualité, nombre			X	

## Mots clés

Microcontrôleur

Architecture

Structure

• Logique

Horloge

Fréquence

RISC

Bus de données

Instructions

# Compte rendu

Ce document publié par Atmel Corporation en 2013 présente la gamme de **microcontrôleurs** vendue par Atmel : AVR.

Ceux-ci fonctionnent sur la base d'une **architecture Harvard** modifiée, cela signifie que la **mémoire** stockant le programme et la **mémoire** dans laquelle est située les données du programme sont séparées en deux. Il est d'usage d'utiliser deux **technologies** de stockage **différentes** dans une telle architecture, ici la **mémoire flash** et la **mémoire vive statique** respectivement.

Les **microcontrôleurs** AVR ont un processeur conçu sur l'**architecture RISC** (Reduced Instruction Set Computer : processeur à jeu d'instruction réduit), qui s'oppose à

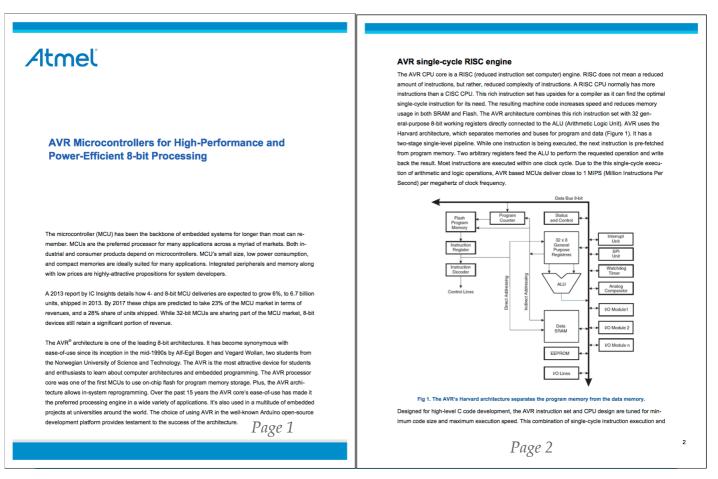
l'architecture **CISC**. Ce principe donne au processeur un nombre **important** d'instructions mais qui exécutent chacune des tâches **élémentaires**, ce qui peut **allonger** la taille du programme pour des opérations complexes mais également **accélérer** le temps d'exécution de ces plus petites instructions.

Les connexions entre les différents **périphériques internes** du **microcontrôleur** sont détaillées ainsi que les **interfaces** de sorties qui permettent à l'Homme de **communiquer** avec ce dernier.

## **Avis**

Ce document technique de présentation est très clair et je lui attribuerai la note de 8/10. Il explique pourquoi il est intéressant de choisir les microcontrôleurs AVR mais en restant dans un cadre technique, en présentant le fonctionnement de ceux-ci et leurs différents composants internes. Les schémas sont d'une grande aide pour comprendre le fonctionnement de ce type de microcontrôleur et comment les connexions entre les périphériques internes et externes ont lieu.

Il est d'autant plus intéressant de s'intéresser aux microcontrôleurs AVR puisqu'ils sont majoritairement utilisés à l'IUT GEII. C'est également ce type de microcontrôleur qui sera présent dans notre projet pour remplacer toute la logique câblée de l'époque du Kenbak-1.



high code density delivers computing performance and low power consumption that still leads the industry. Right from the very beginning another aspect has underpinned the success of the AVR architecture. It is the availability of free design and development software, now including tools such as the AVR GCC C/C++ compiler and the Atmel Studio 6 IDE (Integrated Development Environment). This combination of industry-leading 8-bit performance and free development tools has resulted in AVR retaining a significant loyalty among engineers and programmers.

#### Three Families

Atmel has used the AVR CPU in three high-performance and power efficient 8-bit MCU families: the entry-level tinyAVR $^{\circ}$ , the mid-range megaAVR $^{\circ}$ , up to the most recent family, the AVR XMEGA $^{\circ}$ .

The tinyAVR devices are optimized for applications that require performance, power-efficiency and ease-of-use in a small package. Capable of operating at just 0.7V, the devices integrate an ADC, Flash, EEPROM and a brown-out detector. In addition the chips provide for hardware debug for fast, secure, and cost-effective in-circuit firmware troubleshooting.

The mid-range megaAVR is more suited to applications requiring larger amounts of code. Offering performance up to 20 MIPS, the range offers a wide selection in terms of memories, pin counts and peripherals (Figure 2). There are specialized parts with USB, LCD controllers, CAN, LIN, and power-stage con-

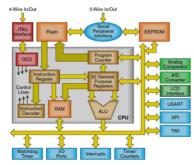


Fig 2. The megaAVR CPU and peripheral units provide power and flexibility

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The AVR XMEGA MCUs are composed of various fundamental blocks including the AVR CPU, SRAM, Flash, EEPROM, and a number of peripherals. The AVR XMEGA instruction set also supports 16-bit register access and 32-bit arithmetic. A key feature of the family is the use of power-saving peripherals, achieved via the device's highly innovative Event System. This is a set of features that allows peripherals to interact without intervention from the CPU. It allows peripherals to send signals directly to other peripherals, ensuring a short and 100% predictable response time. When using the capabilities of the event system, it is possible to configure the chip to do complex operations with very little intervention from the CPU. This saves both valuable program memory and execution time.

All the 8-bit AVR devices use the company's picoPower® technology. This includes an optimized balance of high-performance and low-leakage transistors, low-voltage operation, various low-power and sleep modes with fast wake up, and the use of hardware DMA. Plus the AVR XMEGA features the Event System that offloads work from the CPU to save power and provide consistent interrupt reaction times. Key performance characteristics include operation over 1.8 to 5.5V, consumption of 200uA per MHz in active mode, 0.1uA in power-down mode with full RAM retention, 0.6uA in power-save mode (with a 32kHz crystal oscillator running), and less than 1us wake-up time.

#### Applications and the IoT

The 8-bit AVR MCUs have seen a multitude of design wins in virtually all market sectors. In addition to the general-purpose MCUs described previously, there is a wide range of application-specific AVR based devices suitable for lighting, smart battery, industrial and automotive applications among many others. A huge and fast growing application area is wireless. In fact, RF is fast becoming a standard peripheral in MCUs of all sizes and bandwidths. The opportunities in wireless are certainly many – and none more so than in the Internet of things (loT).

Worldwide wireless infrastructure makers have predicted that by 2020 there will be 50 billion mobile wireless devices connected to the Internet. However, the major wireless players will not entirely dominate this growing arena. Jim Tully, Research Director at market analyst Gartner Group, notes: "Our research says that by 2018, 50% of the Internet of things solutions will be provided by startups which are less than three years old. We can estimate what the internet of things will be like now. But we know that most of the things that will exist in 2018 we can't even conceive of because they haven't been invented yet."

While there is little doubt that low-power 32-bit MCUs will take a share of the market, the opportunity is still highly significant for 8-bit MCUs with low-power demands for the multitude of embedded RF devices that will be required. A primary example of an AVR based device that is well placed to take advantage of these applications is the Armega256RF (Figure 3). This IC is an IEEE 802.15.4-compliant single-chip wireless solution suitable for ZigBee® RF4CE, IPv6 / 6LoWPAN and ISM (industrial, scientific, medical) wireless applications.

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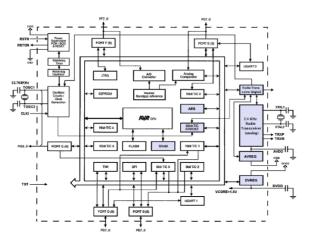


Fig 3. The ATmega256RF combines AVR ease-of-use with a high-performance RF link.

The device combines an AVR MCU and a best-in-class high-sensitivity 2.4GHz RF transceiver, which offers data rates from 250-kbit/s up to 2-Mbit/s. It offers 64K to 256K of Flash and consumes up to 50% less current in some operating modes. It allows for 16MHz operation at only 1.8V supply voltage and gives a fast wake-up time from sleep mode to active modes. In addition to this, it implements various power-down modes, such as a wake-on-radio feature, which keeps the RF transceiver active while the microcontroller sleeps, further enhancing efficiency.

## Conclusion

The ease-of-use, high performance, power efficiency and tight code density capabilities of the AVR architecture make it a very serious proposition for design engineers working in a wide range of applications

Page 5

and markets. They are ideally suited for wireless and the vast opportunities opening up with the internet of things. There is a vast breadth and range of 8-bit AVR MCUs available. The last 15 years have certainly been eventful for the AVR, and it the next 15 will be even more so.



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# Annexe 4 I Architecture and programming of 8051 MCUs

## Identification

Auteur : Milan Verle

• <u>Titre</u>: Architecture and programming of 8051 MCUs

• Éditeur : MikroElektronika

• <u>Date de 1<sup>ère</sup> parution</u>: 1<u>er</u> janvier 2007

## Évaluation du contenu

Critère d'évaluation	Faible	Moyen	Bien	Très bien
Degré de fiabilité de l'informatique			X	
Utilité, accessibilité, pertinence de ces informations				X
Utilité des illustrations				X
Qualité, nombre			X	

## Mots clés

Microcontrôleur

Architecture

Unité de contrôle

• RISC

Harvard

• Timers

• Programme

Watchdog

Mémoire

# Compte rendu

Ce livre est une introduction à l'architecture et la programmation des microcontrôleurs 8051 introduits par Intel en 1980 et encore utilisés comme base aujourd'hui. Ceux-ci sont basés sur une architecture **Harvard** (mémoires programme et données séparées) et CISC (Complex Instruction Set Computer : microprocesseur à jeu d'instruction étendu).

Le premier chapitre explique assez généralement ce qu'est un **microcontrôleur**, puis sa mise en marche et son fonctionnement **cyclique**.

Le deuxième chapitre se concentre sur les différents éléments indépendants qui composent le microcontrôleur, tels que :

- les mémoires : ROM (lecture seule), RAM (accès aléatoire), EEPROM (effaçable électriquement et programmable).
- les <u>registres</u>: mémoire **temporaire rapide** d'accès pour stocker les opérandes et résultats des calculs exécutés par le processeur.
- le <u>pointeur d'instruction</u> : un nombre qui définit la **prochaine** instruction qui va être exécutée par le processeur.
- le <u>processeur</u> : composé du **décodeur** d'instructions, de l'UAL (**U**nité Arithmétique et Logique) et de l'accumulateur. Il s'occupe de l'exécution du programme et de la **communication** avec les autres composants.
- l'<u>oscillateur</u>: l'horloge interne synchrone qui **régit** la vitesse de fonctionnement de tout le microcontrôleur.
- les timers: des éléments utiles pour compter des évènements ou exécuter un programme à intervalles de temps réguliers.
  - le <u>port série</u> : moyen de **communiquer** entre plusieurs microcontrôleurs.

## **Avis**

Je noterai ce document 7/10 pour la simplicité des explications des différents termes techniques. L'assemblage des composant présents dans chaque microcontrôleur est explicité en détail. Cela aide à comprendre le fonctionnement général des différents souséléments et la façon dont il est possible de les utiliser sans pour autant rentrer dans le code informatique ésotérique. Plus de détails seraient pourtant intéressants sur certains périphériques présentés.



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2.8 8051 Microcontroller Interrupts

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5. Assembly Language

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6.1 Basic connecting 6.2 Additional components

6.3 Examples

7. Development systems

7.1 At the end - from the beginning... 7.2 Easy8051A Development System

# Annexe 5 I Internet of Things System Design with Integrated Wireless MCUs

## Identification

• <u>Auteur</u>: Kavita Char

• <u>Titre</u>: Internet of Things System Design with Integrated Wireless MCUs

• Éditeur : Silicon Labs

## Évaluation du contenu

Critère d'évaluation	Faible	Moyen	Bien	Très bien
Degré de fiabilité de l'informatique				X
Utilité, accessibilité, pertinence de ces informations				X
Utilité des illustrations			X	
Qualité, nombre			X	

## Mots clés

Connexion

Internet

Réseaux

Interaction

• Futur

Interface

Communication

• Sans fil

Intelligent

# Compte rendu

Ce document explique une des utilisations des microcontrôleurs qui a **explosé** depuis quelques années: l'IoT (Internet of Things: Internet des Objets). Ce domaine utilise des microcontrôleurs dotés de **connexions** à **internet**, souvent sans fils, afin de connecter un objet, tel qu'un réfrigérateur, une montre ou même un **casier scolaire** au monde entier.

Il est décrit la façon dont ces objets sont connectés au **réseau**, ainsi que le principe de fonctionnement de base d'un **IoT** (capteurs et données sont analysées par le microcontrôleur). La façon de choisir un microcontrôleur et une technologie sans fil est détaillée. Enfin, sont données des **règles** de conception, notamment la vitesse de **développement** et la basse **consommation** nécessaire du système.

## **Avis**

Je noterai ce document 7/10. Il montre en effet que même après son invention qui remonte à quelques décennies, le microcontrôleur est encore au cœur de la révolution technologique actuelle. Le document s'intéresse aux bons points en matière de choix à réaliser pour l'application voulue. Des exemples et illustrations supplémentaires comme des schémas pourraient être d'une réelle aide à la compréhension de l'écosystème des objets connectés.



# Internet of Things System Design with Integrated Wireless MCUs

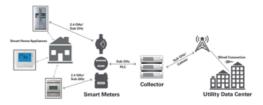
By: Kavita Char, Senior Product Manager, Silicon Labs

#### Introduction

The last few years have seen an explosion in Internet of Things (IoT) devices and connected products such as wireless sensors, smart meters, home automation systems and wearables. The lowered cost of components such as sensors and processors along with increasing wireless connectivity has resulted in many products being made "smart" and able to communicate with each other without human intervention. Successful products must meet often competing requirements including low power consumption, long wireless connectivity ranges and higher processing power. This paper explores how ARM®-based wireless microcontrollers can meet the most demanding requirements of IoT systems.

#### **IoT Sensor Node Requirements**

The network topology of IoT systems is comprised of simple nodes that collect and transmit a limited amount of data to a central controller or gateway which provides connectivity to the Internet and cloud services. Nodes and gateways must be designed to minimize power consumption, provide reliable and robust network connections and extend wireless connectivity range as far as possible.



**Typical Wireless Metering Architecture** 

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At the heart of IoT systems is a processor unit or microcontroller (MCU) that processes data and runs software stacks interfaced to a wireless device for connectivity. Requirements for both the MCU and wireless device are specific to the end application and system requirements. Advanced IoT sensor nodes consolidate sensor functions and use either an 8-bit MCU or a 32-bit device to run a small radio frequency (RF) protocol stack. These devices are typically battery powered and connect to gateways where heavier processing and data transmission occurs.



Wireless Sensor Node Architecture

Sensor Nodes typically transfer small amounts of data and often have to operate on batteries for several years. The devices must also be portable, reliably connected and able to operate under varied environmental conditions regardless of RF interference or physical barriers. Because these devices are part of networks, the setup of networks, aggregation of sensor data and display of information must also be considered. The combined selection of the appropriate MCU and wireless or RF connectivity for these devices as well as development tools and software stacks for application development are critical to their successful design.

#### Selecting a Microcontroller (MCU)

Sensor node selection is largely a factor of the function and purpose designers are trying to fulfill. For a simple end sensor node that senses and transmits data a few times a day, an 8-bit MCU might be the correct answer. However, for advanced end nodes or gateway devices that build in intelligence or need to run an RF protocol stack or other sophisticated algorithms, a 32-bit MCU is a more appropriate choice. Some 32-bit MCUs such as those based on the ARM® Cortex®M4 core also include a floating-point unit (FPU) that proves useful for implementing complex algorithms.

The higher processing capacity of 32-bit MCUs enables them to complete processing sooner in order to enter sleep mode and preserve power. Additionally, the larger flash and RAM sizes available with 32-bit MCUs allow designers to implement the entire networking stack and application code on the MCU without needing an additional processor in the system.

ARM Cortex-M4 based 32-bit MCUs include an FPU with a DSP instruction set. Matrix multiplication, used in monitoring applications that use multiple sensors to get a more accurate reading than individual sensors, is an operation where fast single-cycle MACs (multiply-accumulate) significantly

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reduce the computation time. A common algorithm to correlate the sensor readings is the Kalman Filter, which relies heavily on matrix multiplications.

Developing applications becomes simpler with the integrated FPU. 32-bit floating-point operations are executed in hardware and the algorithms can be written directly with floating point values, taking advantage of the great dynamic range and precision of floating point numbers. Code can be more easily developed by removing the need for overflow checks needed with fixed-point processors. A good example of where ARM Cortex-M4 based MCUs are useful is when a device combines GPS, accelerometer and gyro measurements to improve location accuracy.

# Selecting the Appropriate Wireless and RF Connectivity Solution

Considerations for selecting the RF protocol/technology are link budget, energy consumption and cost. Wireless developers must determine whether a Sub GHz or 2.4 GHz transceiver will best serve their application needs. Given the high profile of 2.4 GHz wireless standards such as Bluetooth® and Wi-FI™, many manufacturers assume that 2.4 GHz is the de facto transceiver frequency of choice. Wi-Fi provides high data rate connectivity and is the most widely used protocol for bandwidth-intensive applications such as wireless cameras, while Bluetooth provides easy point-to-point connectivity with smart phones, which most people use to control their connected home

Transceivers based on 2.4 GHz offer high data rates (greater than 1 Mbps) and a small antenna (less than one-third the size of a 900 MHz antenna) and are suited for short-range consumer electronics devices. However, a 2.4 GHz radio has limited range, poor wall penetration and higher power consumption. The high data rates require a wider receiver channel bandwidth, which further limits the sensitivity and range. In addition, the 2.4 GHz spectrum is crowded and subject to significant interference from Wi-Fi devices, Bluetooth nodes and microwave overs.

Many IoT sensor nodes have relatively low data rate requirements. For these applications, sub-GHz radios offer substantially higher range than 2.4 GHz radios. Sub GHz radios also have much lower power consumption and can provide connectivity for devices that must operate for years on a single battery. These factors, combined with low system cost, make Sub GHz transceivers ideal for low data rate applications that need maximum range and multi-year battery life, such as smoke detectors, door/window sensors and outdoor systems such as weather stations and asset tracking.

One of the main advantages of using Sub GHz wireless is its long-range capability and ability to effectively pass through walls and other barriers. Narrowband transmissions can transmit data to distant hubs, often several miles away, without hopping from node to node, thus reducing the cost

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of deployments with fewer base stations/repeaters. RF waves at lower frequencies can travel longer distances for a given output power and receiver sensitivity.

Achieving good range depends on the antenna gain, receiver sensitivity and transmitter power. The antenna gain is usually limited by cost and device form factor. Receiver sensitivity sets the lower limit on power that can still be received and understood and receiver sensitivity determines how well it can distinguish the desired transmission from other signals and noise in the area. Thus, having a receiver with both good sensitivity and selectivity makes it possible to achieve longer range. A primary factor affecting radio sensitivity is the data rate. The lower the data rate, the narrower the receiver bandwidth is and the greater the sensitivity of the radio.

On the transmitter side, range is determined by the output power level. A 6 dB increase in link budget will double the range in an outdoor, line-of-sight environment. However, regulatory standards limit the allowed output power, and increasing the transmitter power also increases the current consumption, which can have a negative effect on battery life.

While many of the existing Sub GHz networks use proprietary protocols and are closed systems, the industry is moving towards standards based, interoperable systems. The IEEE 802.15.4 standard is gaining popularity worldwide and is being adopted by various industry alliances such as Wi-SUN and ZigBee. Designers should also consider a transceiver's support for mandatory features in Sub GHz bands defined in the 802.15.4 standard.

Silicon Labs' family of EZRadioPRO Sub GHz transceivers have shown 8 to 10 miles of range in both high frequency bands and low frequency bands using standard GFSK modulation. A unique feature of EZRadioPRO is the ability to support ultra-narrow band applications all the way down to 100 bps in a 200 Hz bandwidth. This allows extremely long range communication with standard GFSK modulation for low data rates. Transceivers with programmable data rates such as EZRadioPro allow developers to trade off higher data rates and sensitivity to fine tune the data rate so the radio transmits in the least amount of time.

#### **Simplifying Design with Integrated Components**

Thus far we have discussed MCU and wireless requirements separately. For an IoT system, however the combination of MCU and wireless device selection and their interaction must be considered together. Instead of using discrete components, designers now have the ability to make use of integrated devices that combine MCUs and transceivers. By taking advantage of chips that integrate the two devices, designers do not have to worry about interconnections between the radio and MCU, making for simpler board design, more straightforward design processes and less susceptibility to interference due to shorter bond wires. Designers are also able to rely upon a fully

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tested wireless MCU solution as a starting point for their development. Examples of devices that fulfill these criteria include the Silicon Labs EZR32<sup>™</sup> family of wireless MCU devices.

By making use of single chips that combine ARM Cortex-M based MCUs and radio transceivers, board component count, board layout and overall cost can be reduced. Devices such as the EZR32 wireless MCUs from Silicon Labs integrate ARM Cortex-M3 or Cortex-M4 MCUs with EZRadio and EZRadio/RO transceivers. In addition to ensuring that transmitters provide sufficient power and receivers provide the necessary sensitivity, designers should also make sure the necessary peripherals and communication interfaces are supported. The high power +20dbm transmitters and receiver sensitivity of up to -133dBm of EZR32 wireless MCUs makes them ideal for low data rate and long range applications.

#### **Meeting Low Power Requirements**

One of the main considerations in IoT implementations is the power consumption of the whole system. Typical applications run on batteries that are expected to last for up to 20 years. In most of these applications, the MCU typically stays in low-power sleep mode for a dominant portion of the time, waking up only once in a while to read sensors or to transmit and receive some data.

There are two aspects to the power consumption of the MCU subsystem – dynamic power consumption when the MCU is active, which is proportional to the clock frequency, and the static power related to the leakage current (mostly constant) that plays a bigger role in sleep states. Thus, the total power consumption is affected by the active mode current, the sleep mode current and the amount of time spent in active mode. In applications that spend the majority of the time off, sleep current can be even more important than active current. With higher processing speeds, 32-bit MCUs can conserve power by completing processing tasks faster and entering sleep mode sooner. ARM Cortex-M4 based MCUs with an integrated FPU can further reduce the processing and run-time of complex algorithms. The wireless radio transceiver current consumption in sleep mode transmit and receive mode are also important factors in determining overall system power consumption.

Selecting devices that allow for peripherals to interact with each other and for sensors to be monitored without waking the CPU can greatly reduce the system's total power consumptions. The integrated ESR23 wireless MCU is an example of such a device, with a peripheral reflex system that allows peripherals to interact with each other without waking up the CPU and low energy sensor interface that allows up to 16 sensors to be monitored while the CPU is in deep sleep mode. The new Preamble Sense Mode of the EZRadioPRO transceivers greatly reduces the channel access time with no degradation in sensitivity while reducing the average receive current significantly. These radios require only 8 bits of preamble to detect a valid transmission, compared to the 32-bit requirement of more traditional Sub GHz transceivers. The radio can automatically wake up from sleep and enter receive mode to evaluate the channel based on preamble detection and only wakes

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up the MCU if a valid packet is found. If there is no valid packet, the radio automatically returns to sleep mode without interrupting the host MCU. The combination of MCU and transceiver power saving techniques make integrated wireless MCUs such as the EZR32 from Silicon Labs ideal for battery powered sensor node IoT applications.

#### **Accelerating Software Development**

An important consideration when selecting an integrated wireless MCU for IoT applications is the availability of efficient tools, an integrated development environment and software stacks. For most IoT OEMs, such as lighting and appliance manufacturers, designing and building the application from scratch will require networking, wireless and embedded software expertise. When selecting an integrated MCU designers should evaluate the user friendliness of development tools and the availability of software stacks, device drivers and sample applications that can serve as building blocks for the final product. Additional tools such as radio configuration software, network analyzers and packet trace and debug capabilities can speed development significantly. Many semiconductor suppliers provide some of if not all of the mentioned software tools and components listed above. Silicon Labs has integrated both wireless and MCU development into Simplicity Studio\*\* to provide one development environment for integrated wireless IoT system development.



Silicon Labs Simplicity Studio development platform featuring energy optimization tools

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#### Conclusion

IoT applications have demanding requirements such as high performance, best-in-class RF performance for longer range, lower power for battery powered applications, higher level of integration to reduce component count and BOM costs and a comprehensive toolset of software stacks and sample applications. Fortunately, highly integrated wireless MCU products such as Silicon Labs' EZR32 devices, can provide easy-to-implement solutions that offer the high performance needed to satisfy regulatory standards and consumer needs while providing on-chip features and development tools that make it easier to add wireless connectivity to virtually any embedded application.

Learn more about Silicon Labs' EZR32 Wireless MCUs at <a href="https://www.silabs.com/ezr32">www.silabs.com/ezr32</a> and Internet of Things solutions at <a href="https://www.silabs.com/iot">www.silabs.com/iot</a>.

#### About Silicon Labs

Silicon Labs (NASDAQ: SLAB) is a leading provider of silicon, software and system solutions for the Internet of Things, Internet Infrastructure, industrial control, consumer and automotive markets. We solve the electronics industry's toughest problems, providing customers with significant advantages in performance, energy savings, connectivity and design simplicity. Backed by our world-class engineering teams with unsurpassed software and mixed-signal design expertise, Silicon Labs empowers developers with the tools and technologies they need to advance quickly and easily from initial idea to final product, <a href="https://www.silabs.com">www.silabs.com</a>

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# **Annexe 6 I Intel — The Microprocessor Revolution**

## Identification

• Adresse du site: http://www.i-programmer.info/history/machines/734-intel.html

Nom du site: I ProgrammerDate de publication: 5 août 2010

• <u>Date de consultation</u>: 29 mars 2017

## Évaluation du contenu

Critère d'évaluation	Faible	Moyen	Bien	Très bien
Degré de fiabilité de l'informatique			X	
Utilité, accessibilité, pertinence de ces informations			X	
Utilité des illustrations			X	
Qualité, nombre				X

## Mots clés

Intel

Microprocesseur

Révolution

Composants

• Bits

Compact

Prix

Instructions

Puissance

# Compte rendu

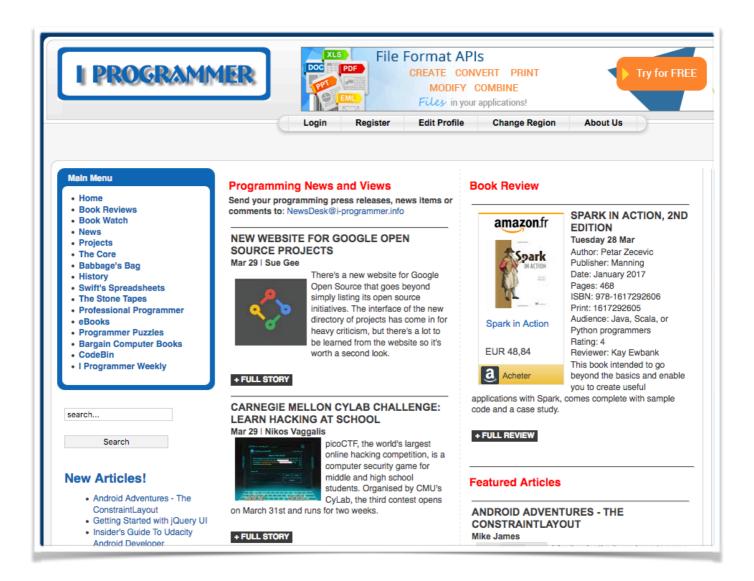
Cet article est un **historique** du microprocesseur dans les grandes lignes et notamment de l'importante participation d'**Intel** dans l'élaboration et la conception de ceux-ci. En 1965, Gordon Moore exposa sa théorie : chaque année, las circuits informatiques contiendraient **deux fois plus** de composants que l'année précédente. Cette théorie se révéla toujours vraie jusqu'à il y a quelques années.

Hoff, Shima et Faggin sont les trois hommes à l'**origine** de l'Intel 4004, le **premier** microprocesseur au monde. Shima et Faggin ont ensuite quitté Intel pour fonder **Zilog**, qui sorti en 1976 le Z80, un microprocesseur très populaire, utilisé dans des ordinateurs tels que les TRS-80, ZX Spectrum ou encore les Amstrad CPC.

Plus tard chez Intel, en 1972, le premier microprocesseur **8 bits** a été conçu : l'Intel 8008. Il est dit que si l'on plaçait 20 autres circuits intégrés avec un Intel 8008, on avait une machine que l'on pouvait appeler « **ordinateur** ».

## **Avis**

Cet historique montre bien l'impact qu'a eu le microprocesseur dans le monde de l'informatique moderne et comment ils ont été conçus. Les processeurs 8 bits apparu il y a plus de 40 ans sont encore majoritairement utilisés aujourd'hui et ne changent plus beaucoup. Cet article pourrait bénéficier de plus de détails, notamment sur les évolutions techniques qu'il y a eu entre les différentes catégories de microprocesseur apparues au fil des années. Je lui attribue la note de 7/10.



### Intel - The Microprocessor Revolution

Thursday, 05 August 2010

#### Article Index

Intel - The Microprocessor Revolution Silicon Rush

The 4004, Hoff, Faggin and Shima The 8008

#### Page 1 of 4

Intel is celebrating the 40th anniversary of its 4004 microprocessor, the first customer programmable chip and the one that led on to the Intel design dominating the processors we use. We look at how all this came to pass.

Silicon Valley is the legendary centre of electronics and computing excellence where big companies, such as Intel, make large sums of money out of very small things indeed.

It started to grow from the seed planted by Shockley Semiconductor. The first big success was Fairchild, set up by the Traitorous Eight who left Shockley after only a year. Robert Noyce and Jean Hoerni went on to invent the basic process that made the integrated circuit a reality, but soon companies all across the States were making use of their idea. Logic gates were to be had from many sources and the role of Silicon Valley was that of just another supplier.

But things were not as quite as they looked.

Fairchild Semiconductors had been set up with the backing of its parent company Fairchild Camera and Instrument Corporation with the option to buy out the eight founding engineers at any time - and with promise of huge profits that's exactly what it did. The result was an even greater fragmentation of the talent that Shockley had gathered together and the eventual birth of the most important of the Silicon Valley companies. Intel.

When the Fairchild Camera and Instrument Corporation bought back its company, in 1969, each of its founders received \$250,000 of stock in return for their \$500 investment.

"For a young guy to walk away with a quarter million dollars a year later was not a bad deal",

Novce commented.

The money was enough to buy the freedom to do something different and many of Noyce's colleagues did just that - they set up their own companies.



Robert Noyce (1927-1990)

Robert Noyce and Gordon Moore stayed on. However, although Noyce was General Manager, with responsibility for 15,000 employees and a company that was still growing, he was beginning to think about alternatives. Despite being an enthusiastic pilot, he was growing bored with having to fly across the country to New York to talk the parent company.



Gordon Moore (born 3rd January 1929 San Francisco)

Gordon Moore, the man known for his theory expounded in 1965 (Moore's Law) that the number of components on a computer chip would double every year, and Robert Noyce were beginning to think about the possibility of starting their own company to do the things they were interested in.

Even though Fairchild was successful, semiconductors were still seen as a high risk and very complex business. There were some good examples of failure, Shockley Semiconductor for example, to dampen an investor's enthusiasm.

Novce and Moore thought that the most profitable thing to do would be to build solid state memory chips. From our point of view this seems obvious but at the time the dominant memory technology was magnetic core and its manufacturers were always managing to push down its price and size to say ahead of any alternatives that might appear.

Semiconductor memory sounded exotic, extravagant and very unknown. It also seemed like a big step to go from the tens of transistors per chip to the hundreds that a solid state memory device would require. Even with their quarter of a million dollars each they needed more cash for the complicated process they were working on.

As Novce noted.

"one of the traps that young companies fall into is running out of money right on schedule but not getting the product out right on

The solution to the cash problem came in the form of Arthur Rock who had helped to arrange the original financing of Fairchild. He had become a successful venture capitalist in San Francisco and he numbered among Noyce's acquaintances.

"It was a very natural thing to go to Art and say 'Incidentally Art, do you have an extra \$2.5 million you would like to put on the crap table?"

recalled Noyce. As it happened he did, but not before grilling Noyce for some time about his aims and hopes for the new company. Rock's method of discovering the truth about a proposition was to talk until the proposer was tired and then talk some more.